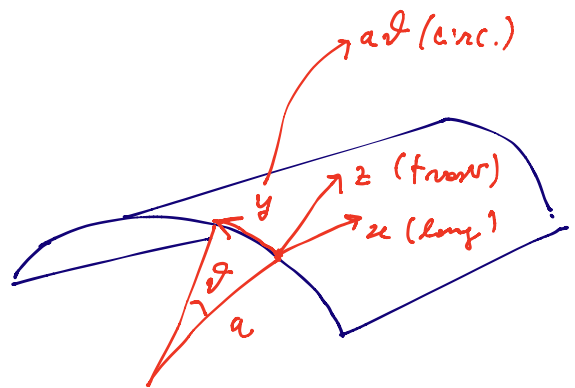


# GUSCI CILINDRICI

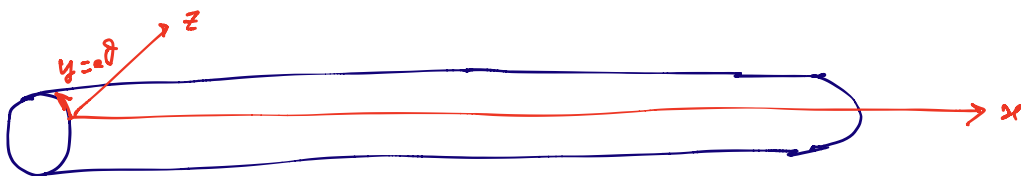
PER LE FORZE NORMALI

$$\begin{cases} n_{\theta\theta} = a p_z \\ n_{x\theta} = \int \left( p_\theta + \frac{1}{a} \frac{\partial n_{\theta\theta}}{\partial \theta} \right) dx \\ n_{xx} = - \int \left( p_x + \frac{1}{a} \frac{\partial n_{x\theta}}{\partial \theta} \right) dx \end{cases}$$



$$\begin{pmatrix} \epsilon_{xx} \\ \epsilon_{\theta\theta} \\ \gamma_{x\theta} \end{pmatrix} = \frac{1}{Et} \begin{pmatrix} 1 & -\nu & 0 \\ -\nu & 1 & 0 \\ 0 & 0 & 2(1+\nu) \end{pmatrix} \begin{pmatrix} n_{xx} \\ n_{\theta\theta} \\ n_{x\theta} \end{pmatrix}$$

$$\begin{cases} \epsilon_{xx} = \frac{1}{Et} (n_{xx} - \nu n_{\theta\theta}) \\ \epsilon_{\theta\theta} = \frac{1}{Et} (n_{\theta\theta} - \nu n_{xx}) \\ \gamma_{x\theta} = \frac{1}{Et} 2(1+\nu) n_{x\theta} \end{cases} \rightarrow \begin{cases} u_x = \int \epsilon_{xx} dx \\ u_\theta = \int \left( \gamma_{x\theta} - \frac{1}{a} \frac{\partial u_x}{\partial \theta} \right) dx \\ u_z = a \left( \epsilon_{\theta\theta} - \frac{1}{a} \frac{\partial u_\theta}{\partial \theta} \right) \end{cases}$$



Se  $p_x = 0$  e  $p_z$  i  $p_\theta$  indipendenti da  $x$ , allora il problema si semplifica

$$n_{\theta\theta} = a p_z$$

$$n_{x\theta} = - \left( \int p_{\theta} dx + \int \frac{1}{a} \frac{\partial n_{\theta\theta}}{\partial \theta} dx \right)$$

$$= - \left( p_{\theta} x + \int \frac{\partial p_z}{\partial \theta} dx \right)$$

$$= - \left( p_{\theta} + \frac{\partial p_z}{\partial \theta} \right) x + f_1(\theta)$$

$$n_{xx} = - \int \left( \cancel{p_x} + \frac{1}{a} \frac{\partial n_{x\theta}}{\partial \theta} \right) dx$$

$$= \int \frac{1}{a} \frac{\partial}{\partial \theta} \left[ \left( p_{\theta} + \frac{\partial p_z}{\partial \theta} \right) x - f_1(\theta) \right] dx$$

$$= \frac{1}{2a} \left( \frac{\partial p_{\theta}}{\partial \theta} + \frac{\partial^2 p_z}{\partial \theta^2} \right) x^2 - \frac{1}{a} \frac{\partial f_1(\theta)}{\partial \theta} x + f_2(\theta)$$

SCEGLIAMO

$$p_x = 0$$

$$p_{\theta} = \hat{p}_{\theta} \sin \theta$$

$$p_z = \hat{p}_z \cos \theta$$

Con questo caso si ottiene

$$n_{\theta\theta} = a \hat{p}_z \cos \theta$$

$$\begin{aligned}
 H_{x\theta} &= - \left( p_\theta + \frac{\partial p_z}{\partial \theta} \right) x + f_1(\theta) \\
 &= - \left[ \hat{p}_\theta \sin \theta + \frac{\partial}{\partial \theta} (\hat{p}_z \cos \theta) \right] x + f_1(\theta) \\
 &= (\hat{p}_z - \hat{p}_\theta) x \sin \theta + f_1(\theta)
 \end{aligned}$$

$$\left. \begin{aligned}
 f_1(\theta) &= C_1 \sin \theta \\
 f_2(\theta) &= C_2 \cos \theta
 \end{aligned} \right\}$$

$$H_{x\theta} = \left[ (\hat{p}_z - \hat{p}_\theta) x + C_1 \right] \sin \theta$$

$$H_{xx} = \frac{1}{2a} \left( \frac{\partial p_\theta}{\partial \theta} + \frac{\partial^2 p_z}{\partial \theta^2} \right) x^2 - \frac{1}{a} \frac{\partial f_1(\theta)}{\partial \theta} x + f_2(\theta)$$

$$\begin{aligned}
 &= \frac{1}{2a} \left[ \frac{\partial}{\partial \theta} (\hat{p}_\theta \sin \theta) + \frac{\partial^2}{\partial \theta^2} (\hat{p}_z \cos \theta) \right] x^2 - \frac{1}{a} \frac{\partial}{\partial \theta} (C_1 \sin \theta) \\
 &\quad + C_2 \cos \theta
 \end{aligned}$$

$$= \frac{1}{a} \left[ \frac{1}{2} (\hat{p}_z - \hat{p}_\theta) x^2 + C_1 x + C_2 \right] \cos \theta$$

Gli spostamenti (in generale) sono [DIMOSTRARE]

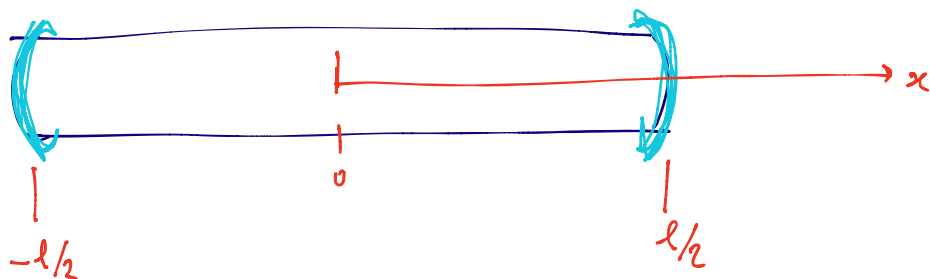
$$Et u_x = \int n_{xx} dx - \nu \int n_{\theta\theta} dx$$

$$Et u_\theta = -\frac{1}{a} \iint \frac{\partial n_{xx}}{\partial \theta} dx dx + \frac{\nu}{a} \iint \frac{\partial n_{\theta\theta}}{\partial \theta} dx dx +$$

$$Et u_z = \frac{1}{a} \iint \frac{\partial^2 n_{xx}}{\partial \theta^2} dx dx - \frac{\nu}{a} \iint \frac{\partial^2 n_{\theta\theta}}{\partial \theta^2} dx dx - 2(1+\nu) \int \frac{\partial n_{x\theta}}{\partial \theta} dx$$

-  $\nu a n_{xx} + a n_{\theta\theta}$

BUSCIO CILINDRICO APPOGGIATO CON DIAFRAMMI

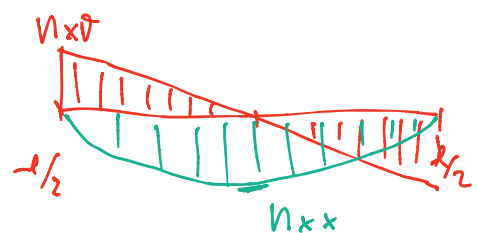


$$u_\theta \left(-\frac{l}{2}\right) = u_\theta \left(\frac{l}{2}\right) = 0$$

$$u_z \left(-\frac{l}{2}\right) = u_z \left(\frac{l}{2}\right) = 0$$

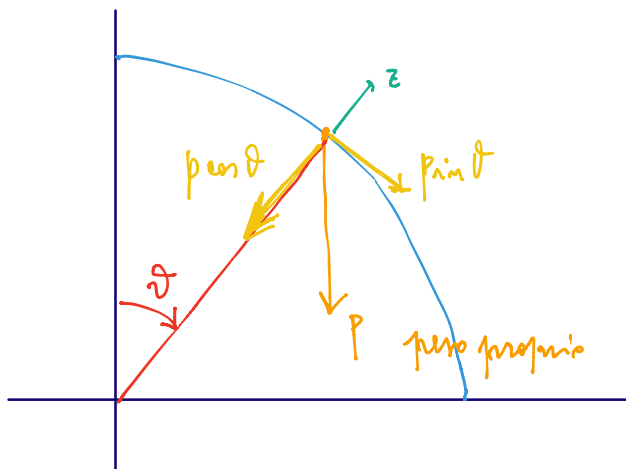
$$n_{xx} \left(-\frac{l}{2}\right) = n_{xx} \left(\frac{l}{2}\right) = 0$$

$$n_{x\theta} (0) = 0$$



$$P_\theta = P \sin \theta$$

$$P_z = -P \cos \theta$$



$$\hat{p}_y = p$$

$$\hat{p}_z = -p$$



costanti di integrazione

$$C_1 = 0 ; C_2 = -\frac{1}{8} l^2 (p_z^1 - p_\theta^1)$$

$$= \frac{1}{4} p l^2$$

$$N_{\theta\theta} = -ap \cos \theta$$

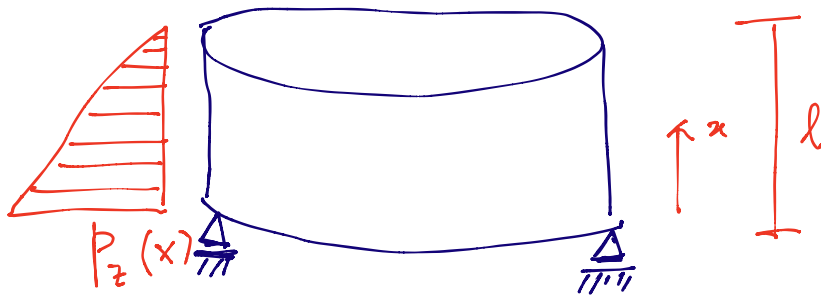
$$N_{x\theta} = -2 p x \sin \theta$$

$$N_{xx} = -\frac{pl^2}{4a} \left[ 1 - \left( \frac{2x}{l} \right)^2 \right] \cos \theta$$

## ALCUNE RIFLESSIONI

- ① sforzo di taglio  $N_{x\theta}$  → trave di lunghezza  $l$  sottoposta a carico uniforme
- ② sforzo normale nelle diagonali  $N_{xx}$  è distribuito lungo  $x$  come il momento flettente della trave

# GUSCIO CIRCOLARE (CILINDRICO) SOGGETTO A CARICO ASSIALSIMMETRICO



- ①  $P_z$  uniforme a  $x$  fissato
- ② avere lo spostamento trasversale  $u_z$  di uniforme a  $x$  fissato
- ③ tutte le derivate rispetto a  $\theta$  sono nulle

per  $P_z(x, \theta) = P_z(x)$

le forze anche nulle zero

$$\begin{cases} n_{\theta\theta} = P_z(x) a \\ n_{x\theta} = 0 \\ n_{xx} = 0 \end{cases}$$

Le componenti di deformazione sono immediate.

$$\begin{cases} \varepsilon_{xx} = \frac{1}{Et} (n_{xx} - \nu n_{\theta\theta}) = -\nu \frac{P_z(x)a}{Et} \\ \varepsilon_{\theta\theta} = \frac{1}{Et} (-\nu n_{xx} + n_{\theta\theta}) = \frac{P_z(x)a}{Et} \\ \gamma_{x\theta} = \frac{2(1+\nu)}{Et} n_{x\theta} = 0 \end{cases}$$

da cui deduciamo gli spostamenti:

$$\begin{cases} u_x = \int \varepsilon_{xx} dx = -\nu \frac{a}{Et} \int p_z(x) dx + A \\ u_\theta = \int \left( \gamma_{x\theta} - \frac{1}{a} \frac{\partial u_x}{\partial \theta} \right) dx = B = 0 \text{ per simmetria} \\ u_z = a \left( \varepsilon_{\theta\theta} - \frac{1}{a} \frac{\partial u_\theta}{\partial \theta} \right) = \frac{P_z(x) a^2}{Et} \end{cases}$$

Applicazione a un tubo di spina d'ogni (diametro  $\gamma$ )

$$P_z = \gamma (1-x) \Rightarrow n_{\theta\theta} = \gamma a (1-x)$$

$$\varepsilon_{xx}(x) = -\nu \frac{\gamma a}{Et} (1-x) ; \quad \varepsilon_{\theta\theta}(x) = \frac{\gamma a}{Et} (1-x)$$

$$u_x = -\frac{\nu a}{Et} \int p_z(x) dx + A$$

delle condizioni al bordo  $u_x(0) = 0 \Rightarrow A = 0$

$$u_x = -\frac{\nu a}{Et} \int \gamma (1-x) dx$$

$$= -\frac{\nu a}{Et} \gamma \left( x - \frac{x^2}{2} \right)$$

$$u_z = \frac{\gamma a^2}{Et} (1-x)$$